

WHAT IS CLAIMED IS:

1 1. A method of processing an input image, comprising:
2 segmenting pixels of the input image based on projections of color values
3 of the pixels onto two-dimensional thresholding planes; and
4 identifying candidate redeye pixel areas in the input image based on the
5 segmented pixels of the input image.

1 2. The method of claim 1, wherein segmenting pixels comprises
2 mapping color values of the pixels into a reference color space.

1 3. The method of claim 2, wherein the reference color space is based
2 on the CIE-Lab color space.

1 4. The method of claim 1, wherein segmenting pixels comprises
2 quantizing pixel color values in at least one color dimension of a color space.

1 5. The method of claim 4, wherein segmenting pixels further
2 comprises projecting pixel color values onto two-dimensional thresholding planes
3 with axes corresponding to non-quantized color dimensions of the color space.

1 6. The method of claim 1, wherein pixels are segmented based on at
2 least one respective redeye color boundary in each two-dimensional thresholding
3 plane.

1 7. The method of claim 6, wherein each redeye color boundary divides
2 a respective two-dimensional thresholding plane into two classification regions.

1 8. The method of claim 7, wherein each redeye color boundary
2 corresponds to a polyline defined by a set of control points in a two-dimensional
3 thresholding plane.

1 9. The method of claim 6, wherein pixels are segmented in the
2 thresholding planes based on first and second sets of different respective redeye
3 color boundaries in each thresholding plane.

1 10. The method of claim 9, wherein a first set of candidate redeye pixel
2 areas are identified from pixels segmented based on the first set of redeye color
3 boundaries and second set of candidate redeye pixel areas are identified from
4 pixels segmented based on the second set of redeye color boundaries.

1 11. The method of claim 10, wherein candidate redeye pixel areas in the
2 first and second sets are merged into a set of candidate redeye pixel areas.

1 12. The method of claim 1, wherein candidate redeye pixel areas are
2 identified based on pixel connectivity.

1 13. The method of claim 1, further comprising segmenting pixels of the
2 input image by computing a redness map from color values of the input image
3 pixels, binarizing the redness map, and identifying candidate redeye pixel areas
4 based on the binarized redness map.

1 14. The method of claim 13, further comprising merging candidate
2 redeye pixel areas identified based on the binarized redness map with candidate
3 redeye pixel areas identified based on the projection of color values onto the two-
4 dimensional thresholding planes.

1 15. The method of claim 13, wherein the redness map is binarized
2 based on an adaptive threshold filter.

1 16. A system for processing an input image, comprising a redeye
2 detection module operable to:
3 segment pixels of the input image based on projections of color values of
4 the pixels onto two-dimensional thresholding planes; and
5 identify candidate redeye pixel areas in the input image based on the
6 segmented pixels of the input image.

1 17. A method of processing an input image, comprising:
2 identifying candidate redeye pixel areas in the input image based on a first
3 redeye color model;
4 identifying candidate redeye pixel areas in the input image based on a
5 second redeye color model different from the first redeye color model; and

6 merging candidate redeye pixel areas identified based on the first and
7 second redeye color models into a set of candidate redeye pixel areas.

1 18. The method of claim 17, wherein each of the first and second redeye
2 color models respectively corresponds to a mapping of color values of pixels of
3 the input image into a reference color space and a redeye color boundary for
4 segmenting pixels of the input image in the reference color space.

1 19. The method of claim 18, wherein the first and second redeye color
2 models correspond to mappings of color values of input image pixels into
3 different respective spaces.

1 20. The method of claim 19, wherein the first redeye color model
2 corresponds to a mapping of color values of input image pixels into a one-
3 dimensional redness color space, and a redness threshold for segmenting input
4 image pixels in the one-dimensional redness color space.

1 21. The method of claim 20, wherein identifying candidate redeye pixel
2 areas comprises computing a redness map from color values of input image
3 pixels, binarizing the redness map based on the redness threshold, and identifying
4 candidate redeye pixel areas based on the binarized redness map.

1 22. The method of claim 20, wherein the second redeye color model
2 corresponds to a mapping of color values of input image pixel into a multi-
3 dimensional reference color space, and a redeye color boundary for segmenting
4 input image pixels in the reference color space.

1 23. The method of claim 18, wherein the first and second redeye color
2 models correspond to mappings of color values of input image pixels into a
3 common reference color space, and different respective redeye color boundaries
4 for segmenting input image pixels in the common reference color space.

1 24. The method of claim 23, wherein identifying candidate redeye pixel
2 areas based on the first and second redeye color models comprises projecting
3 color values of input image pixels onto two-dimensional thresholding planes in

4 the common reference color space, and segmenting input image pixels based on
5 the different respective redeye color boundaries.

1 25. The method of claim 24, wherein segmenting pixels comprises
2 mapping color values of the pixels into the common reference color space.

1 26. The method of claim 25, wherein the reference color space is based
2 on the CIE-Lab color space.

1 27. A system of processing an input image, comprising a redeye
2 detection module operable to:

3 identify candidate redeye pixel areas in the input image based on a first
4 redeye color model;

5 identify candidate redeye pixel areas in the input image based on a second
6 redeye color model different from the first redeye color model; and

7 merge candidate redeye pixel areas identified based on the first and second
8 redeye color models into a set of candidate redeye pixel areas.

1 28. A method of processing an input image, comprising:
2 identifying a set of candidate redeye pixel areas in the input image;
3 projecting input image data into a feature space spanned by multiple
4 features to generate feature vectors respectively representing the candidate redeye
5 pixel areas in the feature space; and
6 filtering candidate redeye pixel areas from the set based on the generated
7 feature vectors.

1 29. The method of claim 28, wherein at least some of the features are
2 contrast features corresponding to respective measurements of local contrast.

1 30. The method of claim 29, wherein the contrast features are
2 orientation independent with respect to the input image.

1 31. The method of claim 29, wherein a given contrast feature weight is
2 computed based on a feature template and a feature plane.

1 32. The method of claim 31, wherein the feature template is a
2 concentric template specifying a contrast measurement between a central basis
3 region and a basis region surrounding the central basis region.

1 33. The method of claim 32, wherein the surrounding basis region is
2 contiguous with the central basis region.

1 34. The method of claim 32, wherein the surrounding basis region is
2 spaced apart from the central basis region.

1 35. The method of claim 31, wherein the feature template is a circular
2 template specifying a contrast between a central basis region and a basis region
3 adjacent to the central basis region.

1 36. The method of claim 35, wherein computing the given contrast
2 feature weight comprises computing contrast values for multiple rotational
3 orientations of the feature template.

1 37. The method of claim 36, wherein computing the given contrast
2 feature weight further comprises assigning an extrema of the computed contrast
3 values to the given contrast feature weight.

1 38. The method of claim 31, wherein the feature template is a circular
2 template specifying a contrast measurement between a pair of basis regions
3 respectively located at opposite ends of a first axis crossing a central region at a
4 first angle and an adjacent pair of basis regions respectively located at opposite
5 ends of a second axis crossing the central region at a second angle different from
6 the first angle.

1 39. The method of claim 38, wherein the first and second axes are
2 orthogonal.

1 40. The method of claim 31, wherein each feature plane is a scalar
2 image computed from input image data.

1 41. The method of claim 40, wherein at least one feature plane
2 corresponds to a mapping of input image data to a grayscale image.

1 42. The method of claim 40, wherein at least one feature plane
2 corresponds to a mapping of input image data to an a-plane in a CIE-Lab color
3 space representation of the input image data.

1 43. The method of claim 40, wherein at least one feature plane
2 corresponds to a mapping of input image data to a redness image.

1 44. The method of claim 31, wherein each feature template is defined
2 by a set of basis regions and a scale factor.

1 45. The method of claim 42 wherein the scale factor specifies a scale for
2 the basis regions relative to a candidate redeye pixel area.

1 46. The method of claim 28, wherein at least one feature is based on
2 pixels near a candidate redeye pixel area and classified as a skin tone pixel.

1 47. The method of claim 28, wherein at least one feature is based on an
2 aspect ratio measurement of the candidate redeye pixel area.

1 48. The method of claim 28, wherein at least one feature is based on a
2 ratio of pixels in a candidate redeye pixel area classified as redeye pixels.

1 49. The method of claim 28, wherein at least one feature weight is
2 computed based on a dynamic range of pixel values in a central basis region.

1 50. The method of claim 28, wherein at least one feature weight is
2 computed based on a standard deviation of pixel values in a central basis region.

1 51. A system of processing an input image, comprising a redeye
2 detection module operable to:

3 identify a set of candidate redeye pixel areas in the input image;
4 project input image data into a feature space spanned by multiple features
5 to generate feature vectors respectively representing the candidate redeye pixel
6 areas in the feature space; and

7 filter candidate redeye pixel areas from the set based on the generated
8 feature vectors.

1 52. A method of processing an input image, comprising:
2 detecting redeye pixel areas in the input image;
3 segmenting glowing redeye pixel areas from non-glowing redeye pixel
4 areas; and
5 re-coloring regions of the segmented glowing redeye pixel areas.

1 53. The method of claim 52, wherein a given redeye pixel area is
2 segmented as a glowing redeye pixel area based on relative numbers of redeye
3 pixels and non-redeye pixels in the given redeye pixel area.

1 54. The method of claim 53, wherein a given redeye pixel area is
2 segmented as a glowing redeye pixel area when the relative numbers of redeye
3 pixels and non-redeye pixels in an oval glint correction region inscribed in the
4 given redeye pixel area exceeds a predetermined threshold.

1 55. The method of claim 52, wherein a given redeye pixel area is
2 segmented as a glowing redeye pixel area based on a measurement of average
3 luminance of pixels in the given redeye pixel area.

1 56. The method of claim 52, wherein re-coloring comprises computing
2 darkening factors for pixels of the glowing redeye pixel areas.

1 57. The method of claim 56, wherein the darkening factors are
2 computed based on pixel distance from respective centers of redeye pixel areas.

1 58. The method of claim 56, wherein re-coloring comprises darkening
2 pixels in the segmented glowing redeye pixel areas based on the computed
3 darkening factors.

1 59. A system for processing an input image, comprising:
2 a redeye detection module operable to detect redeye pixel areas in the
3 input image; and

4 a redeye correction module operable to segment glowing redeye pixel areas
5 from non-glowing redeye pixel areas and to re-color regions of the segmented
6 glowing redeye pixel areas.